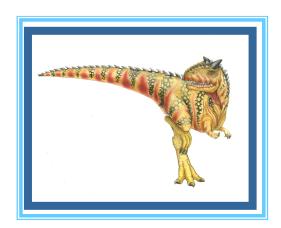
# RINCIPLES OF OPERATING SYSTEMS

# Lecture 26 Bounded Buffer Problem



# Chapter 6: Process Synchronization

- Background
- The Critical-Section Problem
- Peterson's Solution
- Synchronization Hardware
- Semaphores
- Classic Problems of Synchronization
- Monitors
- Synchronization Examples
- Atomic Transactions





### Deadlock

- Deadlock two or more processes are waiting indefinitely for an event that can be caused by only one of the waiting processes
- Let S and Q be two semaphores initialized to 1

 Priority Inversion - Scheduling problem when lower-priority process holds a lock needed by higher-priority process





### **Starvation**

Starvation – indefinite blocking.

A process may never be removed from the semaphore queue in which it is suspended

### Order of arrival retainment:

- **Weak** semaphores:
  - > The thread that will access the critical region next is selected randomly
  - > Starvation is possible
- > Strong semaphores:
  - The thread that will access the critical region next is selected based on its arrival time, e.g. FIFO
  - Starvation is not possible





- Bounded-Buffer Problem
- Readers and Writers Problem
- Dining-Philosophers Problem





### **Bounded-Buffer Problem**

- N buffers, each can hold one item
- Semaphore mutex initialized to the value 1
- Semaphore full initialized to the value 0
- Semaphore empty initialized to the value N.





# **Bounded Buffer Problem (Cont.)**

The structure of the producer process

```
do {
    // produce an item in nextp
    wait (empty);
    wait (mutex);

    // add the item to the buffer
    signal (mutex);
    signal (full);
} while (TRUE);
```





# **Bounded Buffer Problem (Cont.)**

■ The structure of the consumer process

```
do {
      wait (full);
      wait (mutex);
           // remove an item from buffer to nexto
      signal (mutex);
      signal (empty);
           // consume the item in nextc
} while (TRUE);
```

